* Import computer vision
* Save colour keys to track ball

Imports:

Rclpy

Node

Message type for location in 3D

openCV

Class object\_tracker(Node):

Initialize

Create publisher for coordinates to terminal

Create publisher for velocities to bot

Create subscriber for computer vision coordinates

Create subscriber for bots position

Create timer

Create a publisher function to publish the coordinates to

Def

Def main(args=None):

Rclpy.init()

Create instance of class

Try:

rclpy.spin(my\_pub)

Except some kind of interrupts:

My\_pub.destroy\_node()